www.sdmo.com



Energy Solutions Provider

RENTAL generators





GENERATORS SPECIFICATIONS

Generators specifications



Energy Solutions Provider

Genset Ref :	R22C3	R90C3	R110C3	R550C3
Engine :	Mitsubishi	John Deere	John Deere	Volvo
	S4Q2-Z361SD	4045HFS86	4045HFS87	TAD1651GE
Alternator :	LSA 40 M5	LSA 43.2 L8	LSA 44.2 VS45	LSA 47.2 M7
	Reg R438	REG R450	Reg R450	Reg R450
Rated Power (PRP) :	20 kVA	81 Kva	100 Kva	500 kVA
	16KW	65	80KW	400kW
Voltage :	400/230 V	400/230 V	400/230 V	400/230 V
Rated Frequency :	50 Hz	50 Hz	50 Hz	50 Hz
Controller :	NEXYS	TELYS	TELYS	TELYS
		Synchroniser	Synchroniser	Synchroniser
Breaker :	32/4	160/4	160/4	800/4
Dry weight (kg):	794	2100	2140	6082
Tank capacity (L):	153	527	527	1481
Autonomy @ 50% load (h)	45		36.9	26.9

Test report



Energy Solutions Provider

Fiche d'Essais S				Ref: I	FORM-9	187 Indice E	PAGE 1/	2
SPECIFIC TEST RE			Nº ID //d Nº Série	entification / Serial m	n number: umber:	12903 150	angu l	(
	: Ram		_	Contrôles		Plateforme	<u> </u>	
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Electronic regulation		Voltage regulation			Type	/ .		
Marque		Туре:				o de série ou number or ba		
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Pick-up Voltage					-			_
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Intensité pompe fuel		Démarrage /ambt au	tomatique	089		Surcharge alte r overload a	mateur (Tohn)	9
Fuel pump current :	A . U	Auto start/stop circu Défaut pression d'hu			Défaut S	urcharge Alte	mateur (Nexps)	6
Preheating current :	Λ	Low Oil Pressure Sk Défaut température			Alternato	r overíoad fa ta controle /(ait .	+
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Disjoncteur de puissance type / Ci	ircuit breaker	ope: NBA 1608	Inco	o:√60	A loc	llat Ir:	A Im: 7	
Type de disjoncteur :	bipolaire (tripolaire			têtra pola	ire (3P+N)	Ø
Type of circuit breaker	2 pole		3 pole Test homie	e officienting	o (Como	4 pole	1	
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							f (pou	r GE >4	4 KV/		um step load (on			
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PRP : *Prime Running Power*

Prime Power is available for an unlimited number of annual operating hours in variable load applications, in accordance with ISO 8528-1.

Possibility of 1 hour 10 % overload every 12 hours

ESP : Emergency Stand-by Power

The standby power rating is applicable for supplying emergency power in variable load applications in accordance with ISO 8528-1. Overload is not allowed.

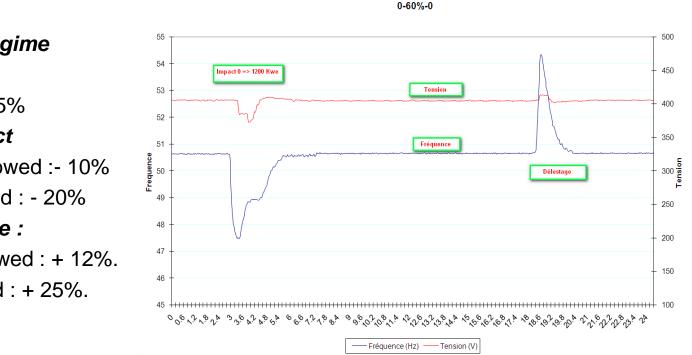


	Operational range values Performance class								
	G1		G2	G3	G4				
∆Maximum F*	-15%	$\left \right $	-10%	-7%	Agreemen				
∆Maximum volta	ge -25%		-20%	-15%	Agreemen				

G2 Class criteria – ISO8528



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• In stabilized regime

Voltage : +/- 2,5 % Frequency : +/- 0,75%

• On Load impact

Frequency drop allowed :- 10% Voltage drop allowed : - 20%

• On load release :

Frequency rise allowed : + 12%. Voltage rise allowed : + 25%.

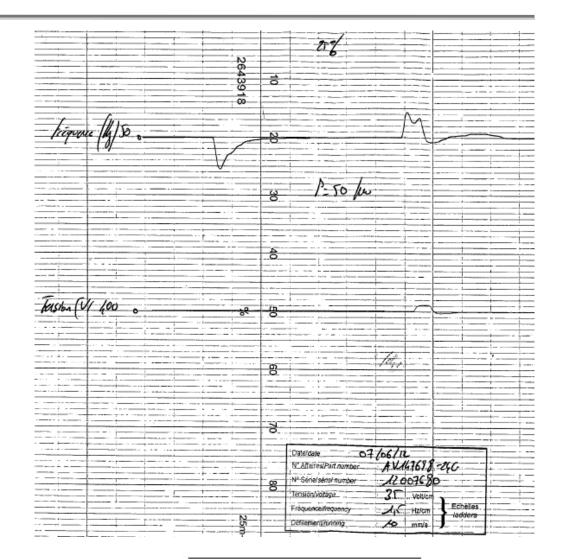
Response time :

Frequency is back within +/- 0.75% of Fn within 5 secs Voltage is back +/- 2.5% within 6 secs

Test Sheet - load impact at 25% load



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Test Sheet - load impact at 50% load



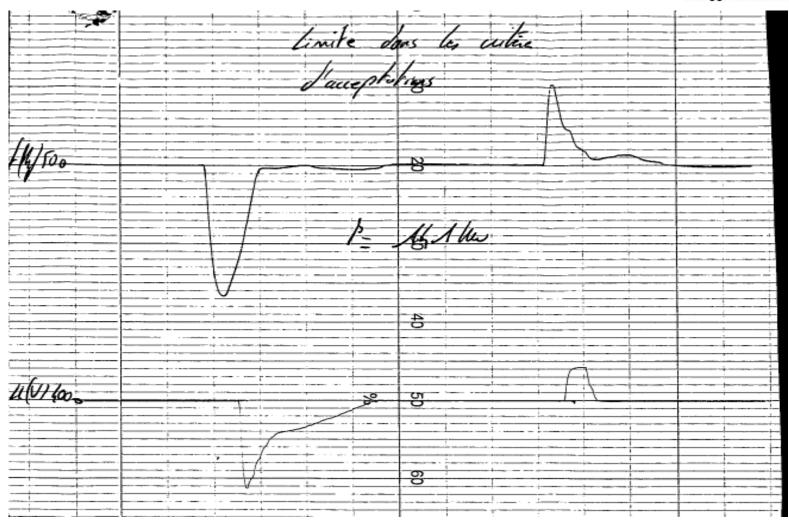
Energy Solutions Provider

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## Test Sheet - Max Load impact within G2 Class



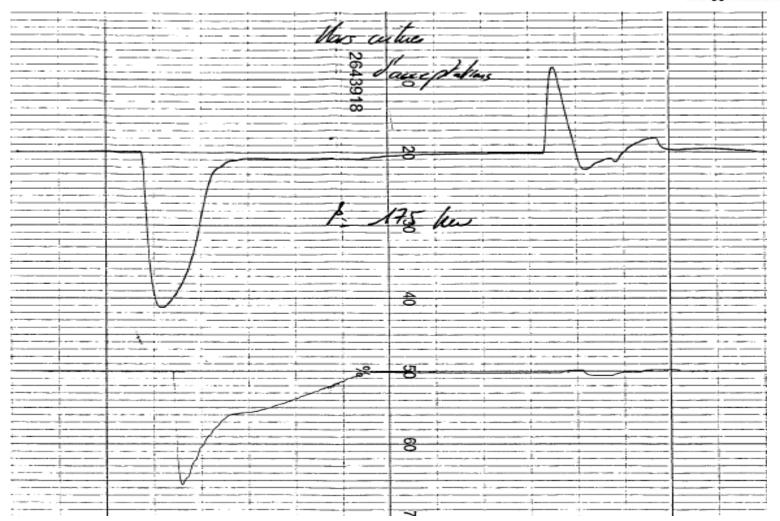
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## Test Sheet - Max Load impact out of G2 criteria



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## Factory Test sheet.



Caractéristiques du groupe / Genset characteristics											
Puissance: <i>A.C</i> KVA Cos phi / Power factor : 0,8 Power Puissance : <i>S.C</i> KW Service/ Duty: PRP Power Tension : <i>hot</i> / <i>ISC</i> V STBY Voltage Intensité :, h.h A Intensity						PRP	¥	1500 tr	engine speed /mn (rpm) r/mn (rpm)	[ Elect Gov ] 49.5 - 50.5 HZ (full load): 50 Mech Gov only ] 50.9 - 52 HZ (no load):	н. нz С. нz
Paliers Stages	F Hertz	L1	J Vol	ts L3	1 11	Ampè 12	res 13	P Kilowatts	Présent Present		ltats/ <i>Results</i> 100 % Pn
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25 %	50	ha	hạo	hao	<u>3</u> 3	<u>3</u> ,2	3.2	Ze		Ampèremètre batterie Battery amperemetre	р. <u>А.</u> А
50 %	50	haci	(ov	had.	62	56.	52	ham	x	Indicateur température eau Water temp. indicator	<u>6 ~ </u>
75 %	50	hci	hçç	hcu.	86	85	K.	60		Chi sompor aster c marcaro	u. <del>{</del> ℃
100 %	50	hau	hạc	hợi	118	Ш	119	80	ð	Indicateur pression huile Oil pressure indicator	3b
110 %	50	hau	hac!	họ,	17,7	127	127	88	B	Lecture fuel présente Fuel gauge	B
IMPACT DE CHARGE MAXIMUM (pour GE >44 KVA) / Maximum step load (only for > 44KVA)											
Dans les critères ISO 8528 CLASSE G2 within ISO 8528 CLASS G2 limits Out of ISO 8528CLASS G2 limits											
Impact de Maximum	-		n			d.	0	KW Echelor maxi ste		information) Max KW Information only) Max KW:	<i>Ң.С</i> кw



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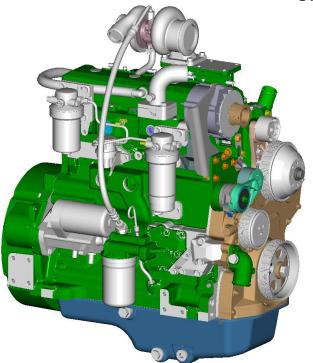
# **ENGINE**

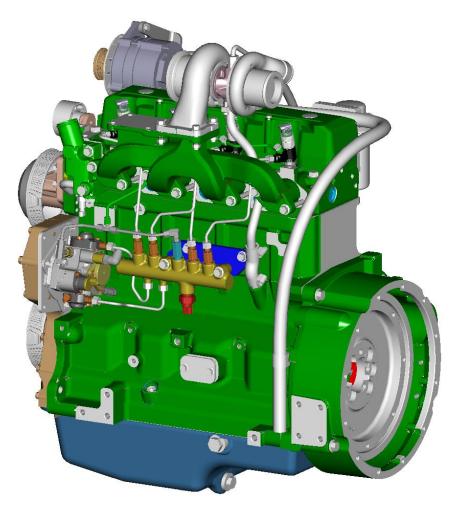
## John Deere 4045HFS86



**Energy Solutions Provider** 

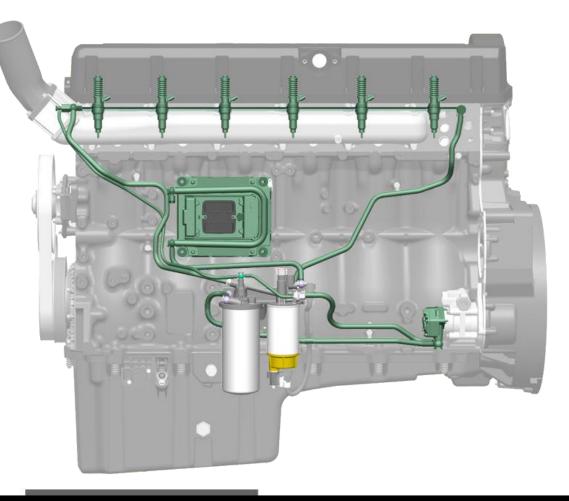
- John Deere Engine 4045HFS86. ٠
  - 4 Cylindres 4,5 litres.
  - ECU engine
  - **Common Rail Technology**







16 litres Engine 6 Cylindres Injector pump Technology Equipped with ECU





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# Maintenance

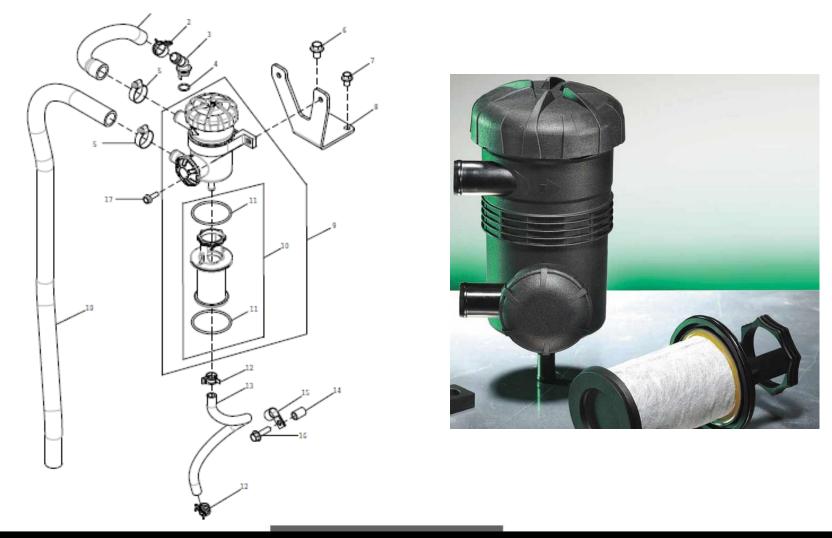


OPERATIONS	Visa	Remarks
Generator set <ul> <li>Check the absence of leaks</li> <li>Check the condition of battery charge</li> <li>Clean the battery terminals</li> <li>Check condition and connections of electrical equipment</li> <li>Clean with compressed air the relays and contactors</li> </ul>		
Engine  • Change engine oil and filter  • Replace fuel filter element(s)  • Check crankcase vent system  • Check engine mounts  • Check engine ground connection		

## Maintenance tips.



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## Maintenance tips



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- John Deere Engine are delivered with a breaking oil
  - Oil change after first 100 hrs.
- Engine filled up with coolant (-26 °deg)

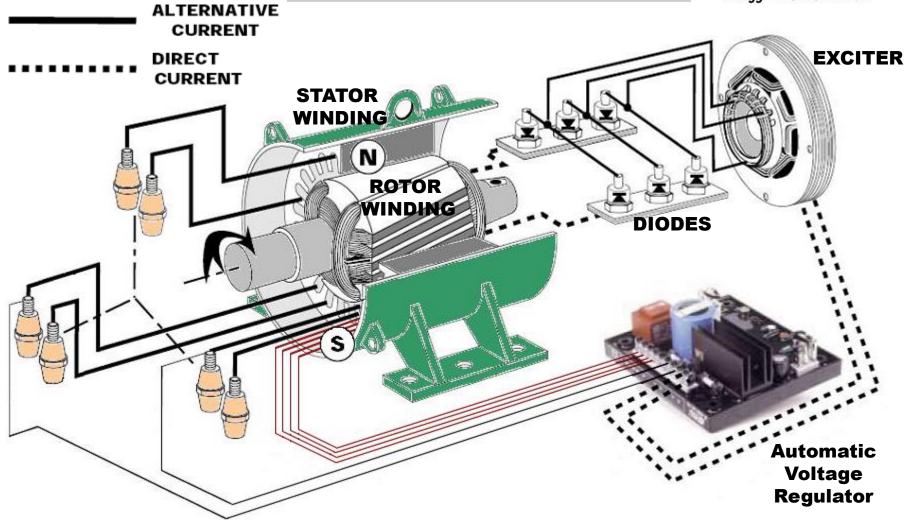


# **Alternateurs - AVR**

## **AREP** description



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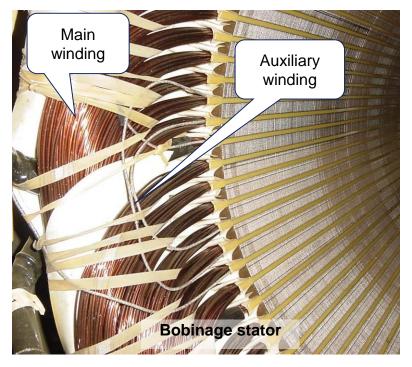
# **AREP** Description



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## **Leroy-Somer Patent**

The 2 auxiliaries windings are inserted during the windings operating of the stator. They have a special protection to achieve a total insulation from the main windings.



### Principle of the auxiliaries:

The first auxiliary winding (e H1) provide a power to the exciter, which is proportional to the output voltage from the stator.

The second auxiliary winding (ie H3) provide a power to the exciter, which is proportional to the output current from the stator.

## **Rotating diodes**



**Energy Solutions Provider** 

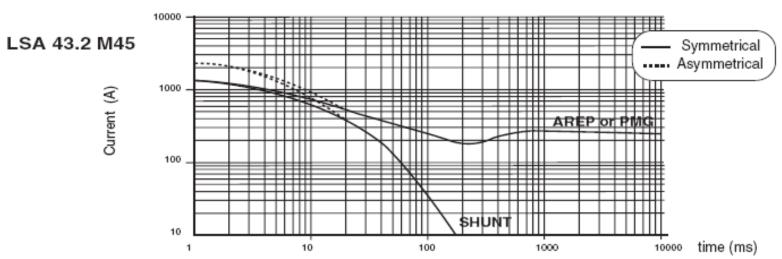




Diode cressent for LSA 47.2. (500 Kva)







#### 3 phase short-circuit curves at no load and rated speed (star connection Y)

300 % of In during 10 seconds is sutained with AREP or PMG regulation.

# Short circuit and overload

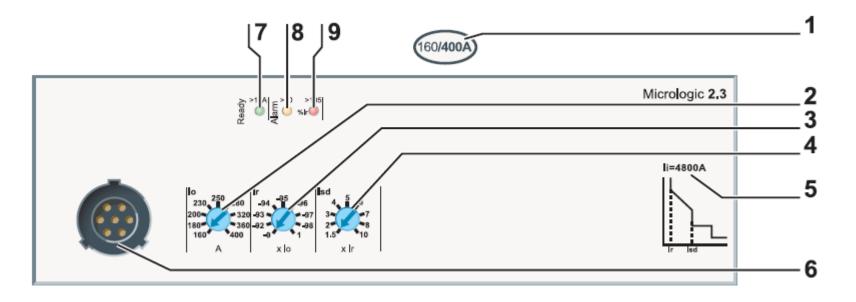


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Protection against short circuit downstream to the machine. The manufacturer value is 300 % of In during 10 seconds Protection realized by:

### - Circuit breaker

Integration of the unity(unit) of control in the circuit breaker. This unity(unit) of control must be adapted to needs



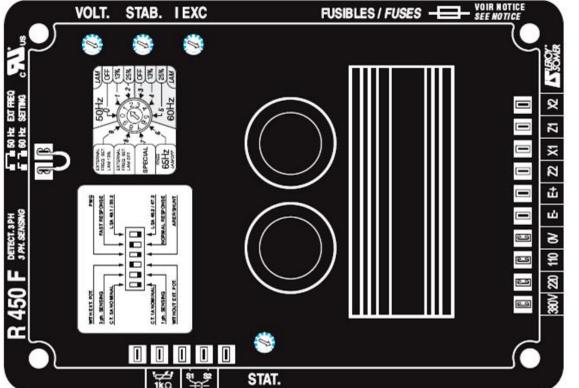
**AVR R450** 



**Energy Solutions Provider** 

LSA46.2 to

LSA50.2



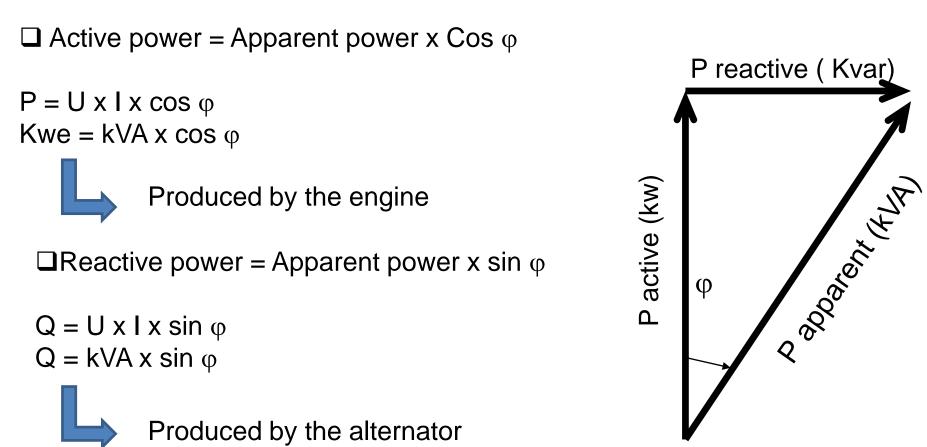


# **Electric notion**

# **Active / Apparent Power**



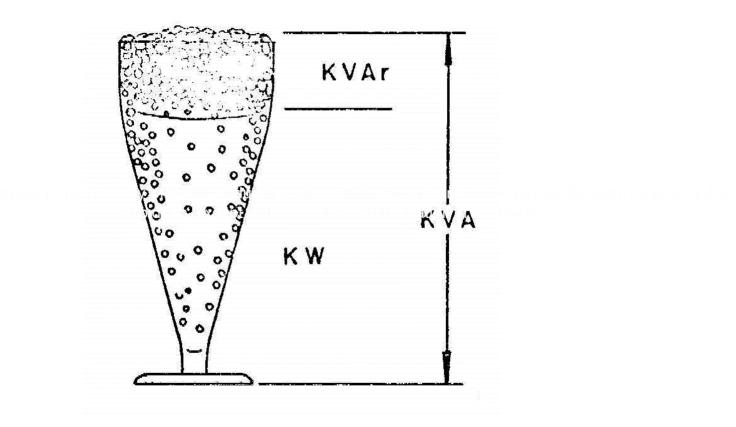
**Energy Solutions Provider** 



## Representation KW, Kvar, Kva.

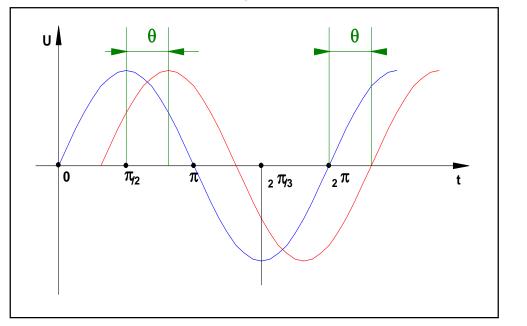


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- In some cases of utilization (supply of electric engines), the current is « late » compared to the voltage. This « delay » is called the power factor  $\ll \cos \varphi$  and its value is very important for the gensets dimensions.
- The power factor  $\cos \varphi$  of one electric engine is very different ۲ between the starting phase and the nominal phase.

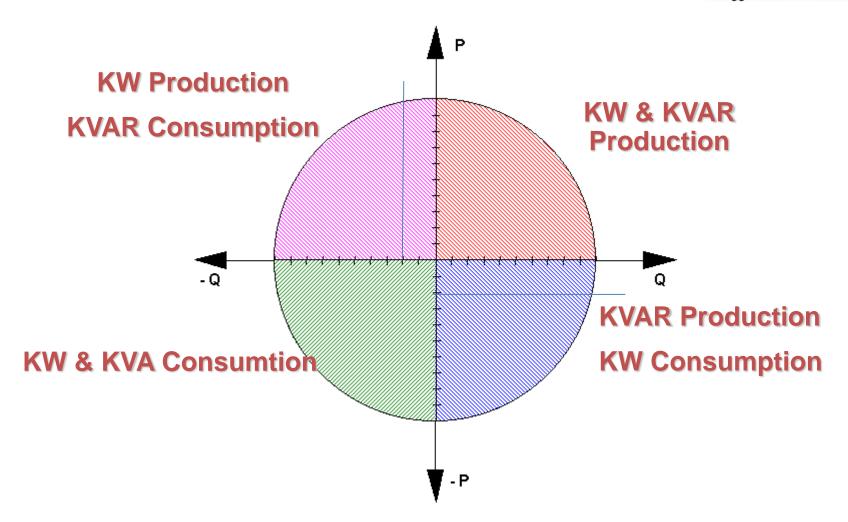


 $\cos \varphi d = \operatorname{can} \operatorname{reach} 0,2$  $\cos \phi n = 0.8 \text{ up to } 0.9$ 

# Kw & Kvar relation Main / Gen Set



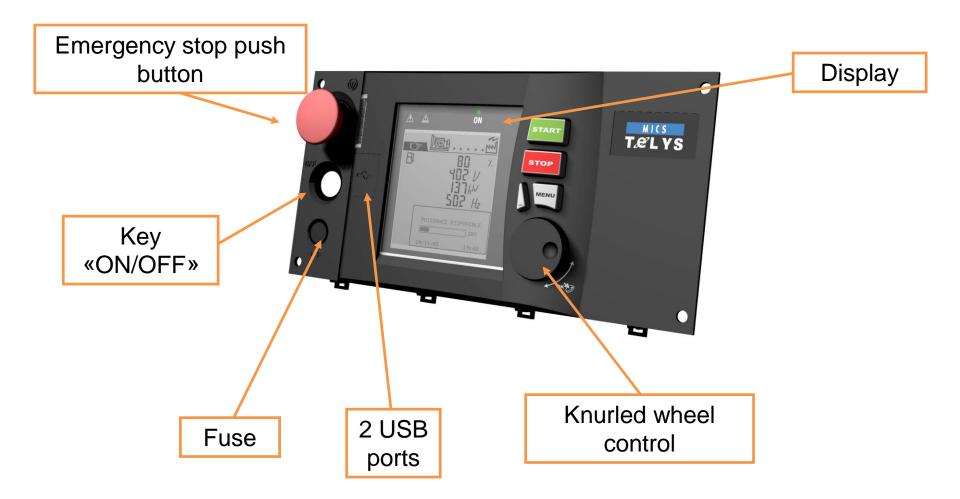
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# **Telys 2 controller**







#### Measurements:

### Electrical :

- ✓ Phase to ground voltages
- ✓ Phase to phase voltages
- ✓ Currents
- ✓ Frequency
- ✓ Active/reactive effective power
- ✓ Power factor
- ✓ Total and partial active/reactive energy meter.

### Engine:

- ✓ Fuel level (%)
- ✓ Oil pressure (Bar/PSI)
- ✓ Coolant temperature (° C/° F)
- ✓ Oil temperature (° C/° F)
- ✓ Battery voltage
- ✓ Charging alternator current
- ✓ Engine speed.



## **Safety features for:**

- ✓ Alternator Min/Max Voltage
- ✓ Alternator Min/Max Frequency
- ✓ Battery Min/Max Voltage
- ✓ Overload
- ✓ Oil pressure
- ✓ Coolant temperature
- ✓ Overspeed / Underspeed
- ✓ Max active / reactive power
- ✓ Reverse active / reactive power







## Additional alarms and Functions



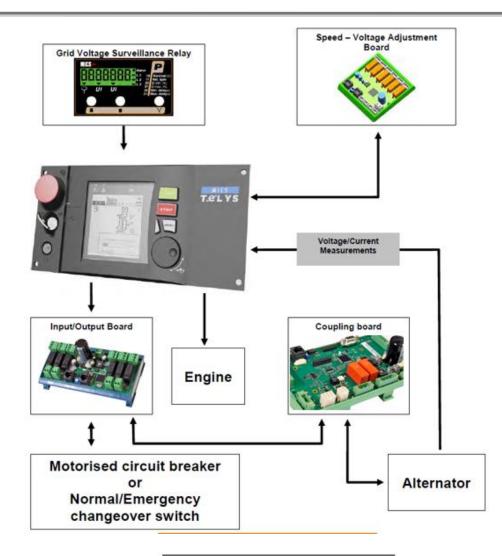
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- Daily service tank low level Fault. (10% approx)
- Alarm Bulk Tank (Retention bund)
- Earth fault triggered
- Low Coolant level Fault (on Volvo only)
- Air preheating.
- Engine coolant preheating

#### Description of componant



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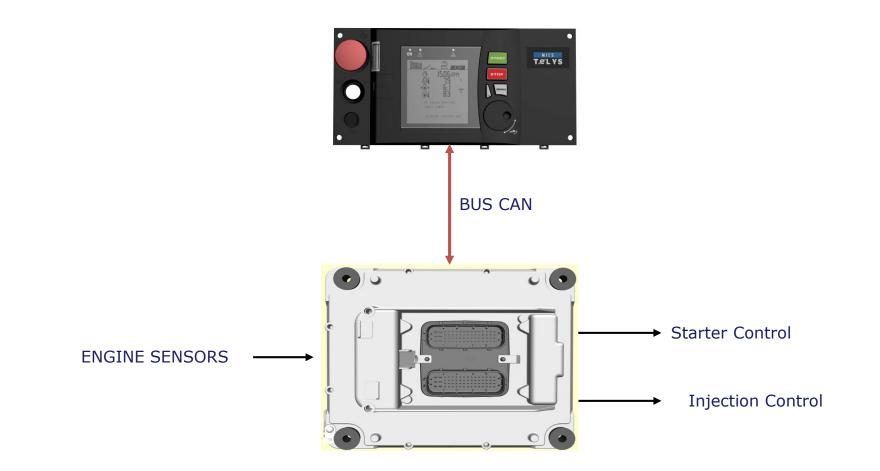


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#### ECU Volvo TELYS 2



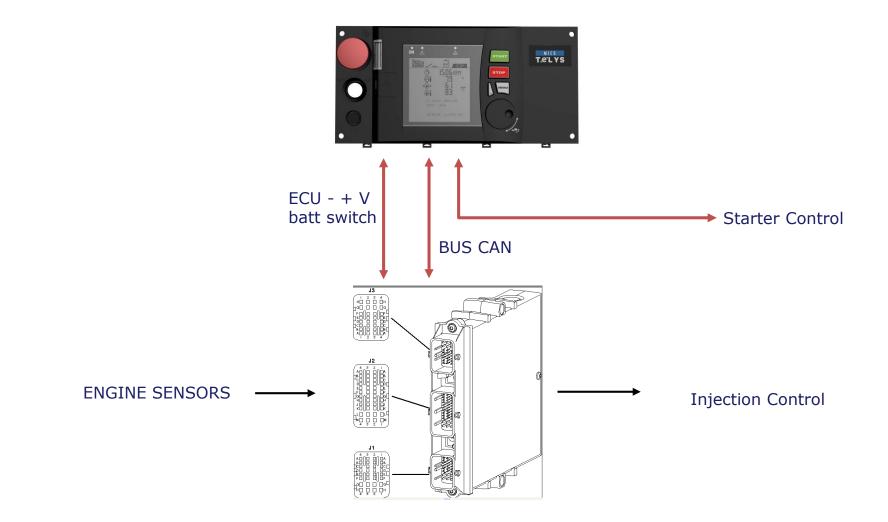
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#### **ECU JDEC Telys**



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#### ✓ USB Connection



<u>Telys  $\rightarrow$  clé USB</u> :

Donwload configuration and events
 (Donwload all)

<u>Clé USB → Telys</u> :

Upload configuration(Upload configuration)

# **SDMO**°

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#### Rental compact



#### **Control Panel**



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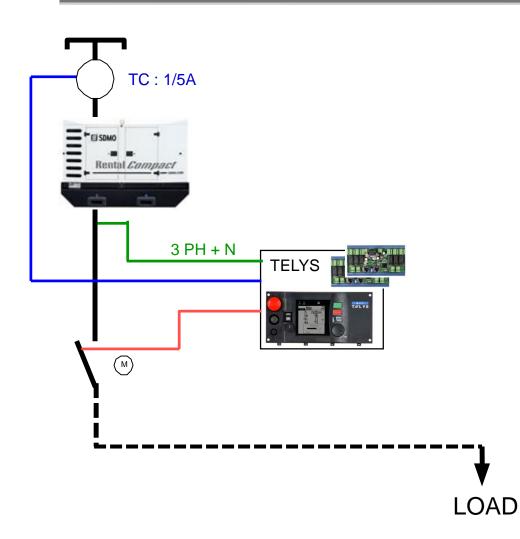
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## Single mode

#### Single mode



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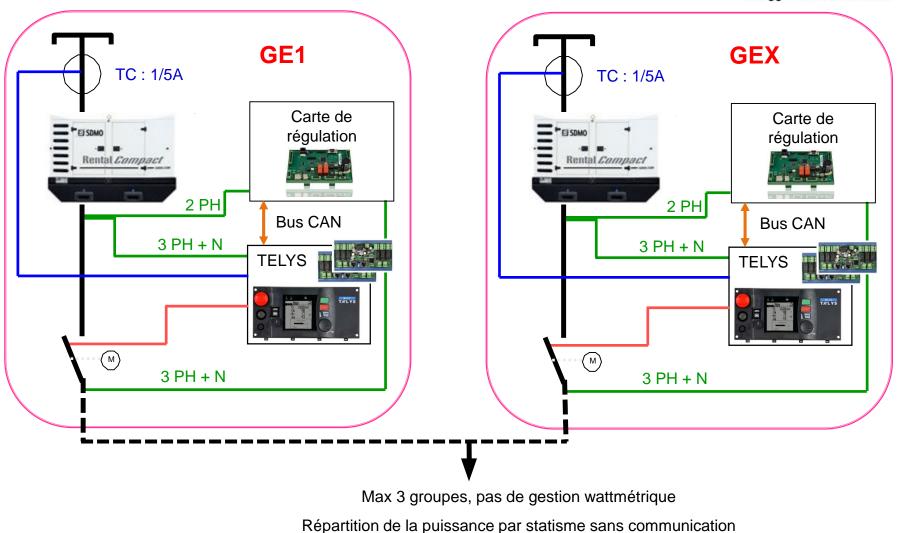
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#### **Parallel mode**

#### **Principle**



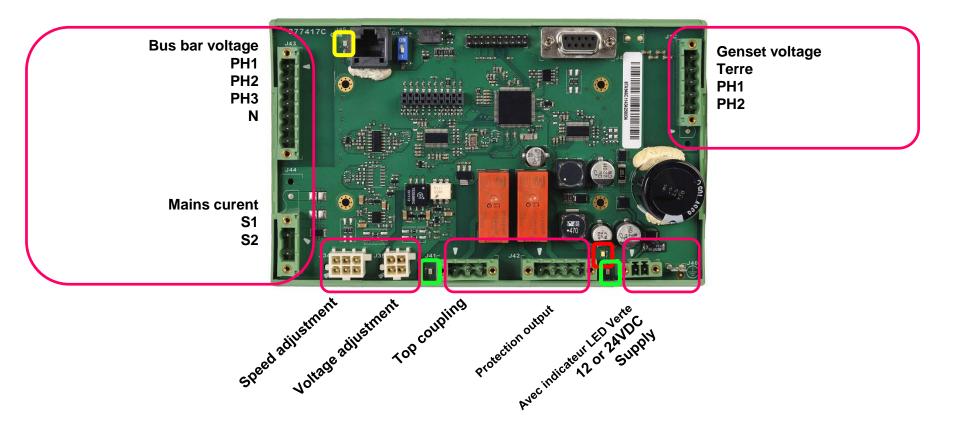
**Energy Solutions Provider** 



#### Coupling board



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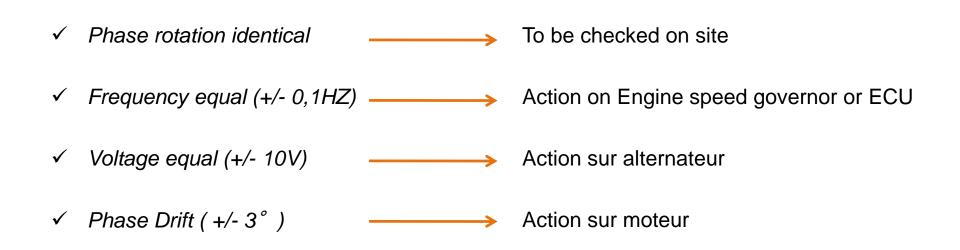


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#### Parallel mode

## Step 1 Synchronisation

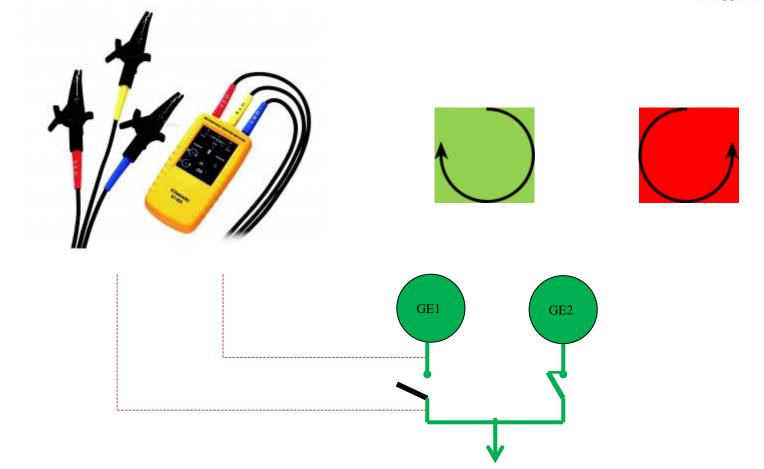




#### Synchronisation : Phase sequence



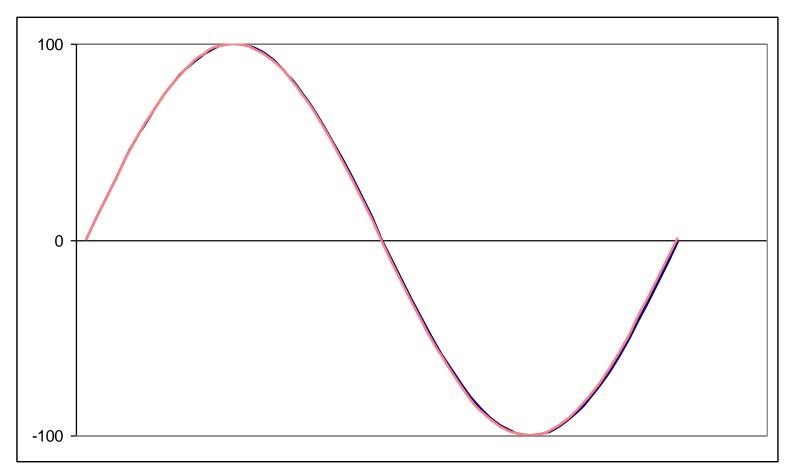
**Energy Solutions Provider** 



#### Synchronisation : Frequency



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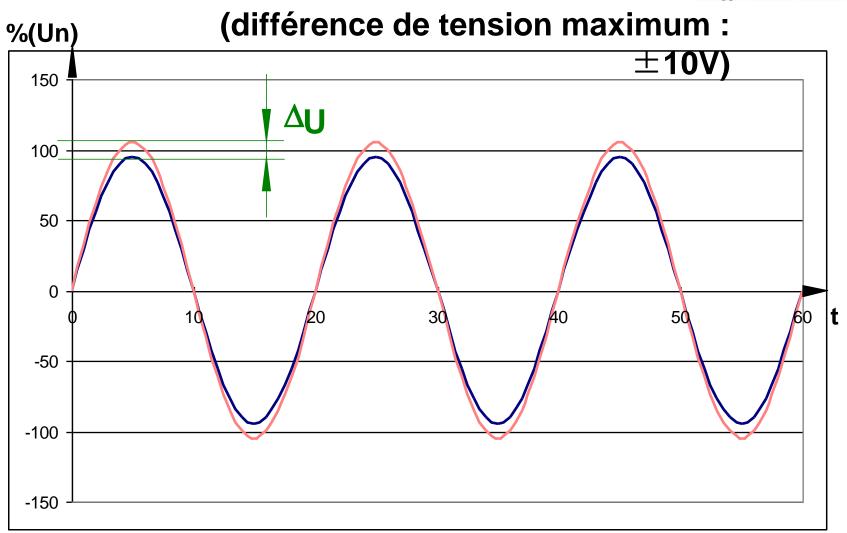


#### (décalage maximum en fréquence : $\pm$ 0,1 Hz)

#### Synchronisation : Voltage



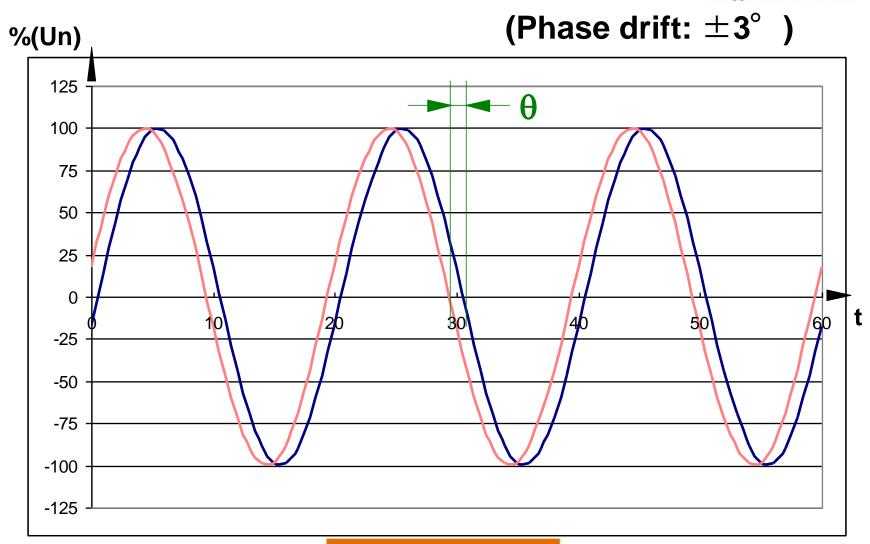
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#### Synchronisation : Phase drift



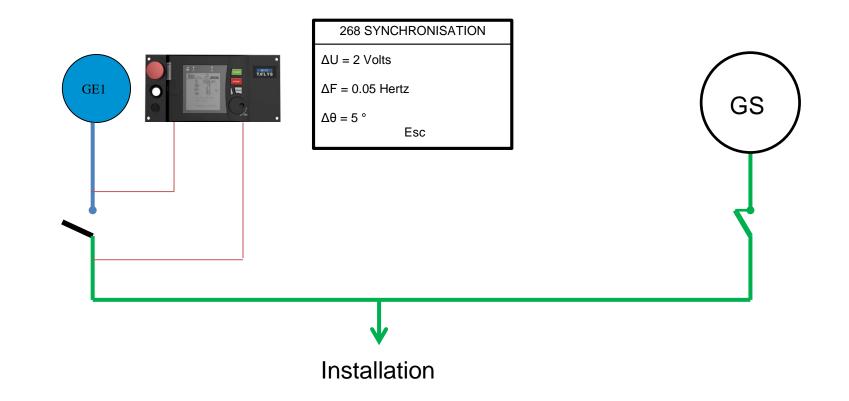
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#### Synchronisation genset to bus bar



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Référence of synchronisation : Bus bar Genset to synchronize : Bleue



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#### **Parallel mode**

## Step 2 Load sharing



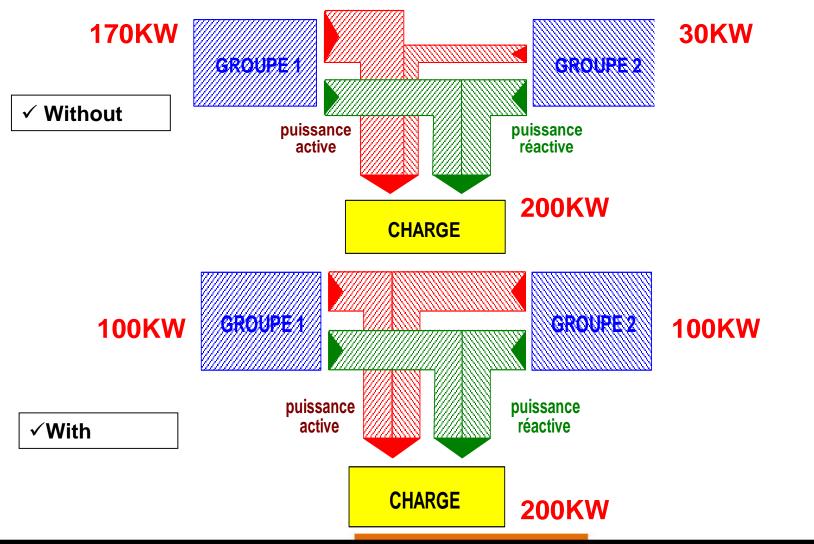
#### • For a single Genset:

- ✓ Active and reactive power depend of the Load and its power factor.
- ✓ An action on the speed regulator will affect the frequency of the supply.
- ✓ An action on the voltage regulator will affect the voltage of the supply.
- For a genset synchronized to another genset:
- ✓ Active and reactive power depends from :
  - the load
  - The behavior of the 2 gensets towards each other.
- ✓ Action on the speed regulator will affect the active load sharing (KW) and the bus frequency.
- ✓ Action on the voltage regulator will affect the reactive load sharing (KVAR) and the bus voltage .

#### Load sharing

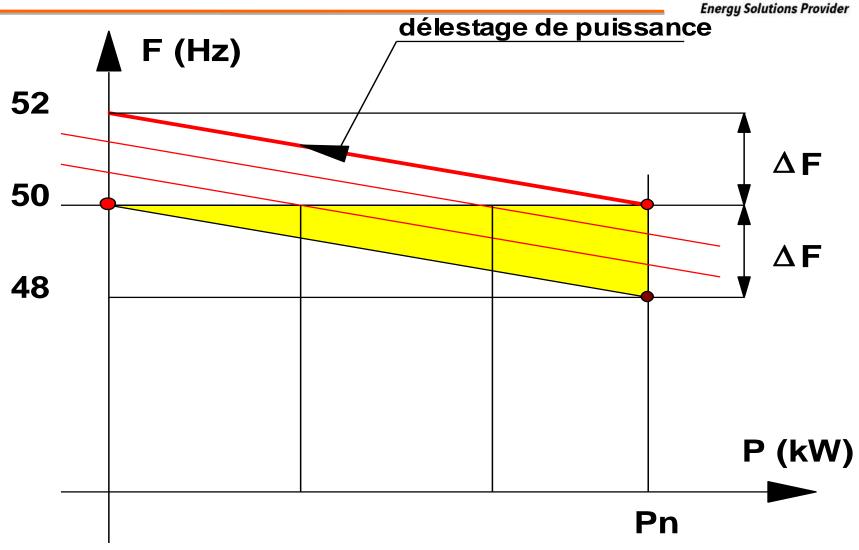


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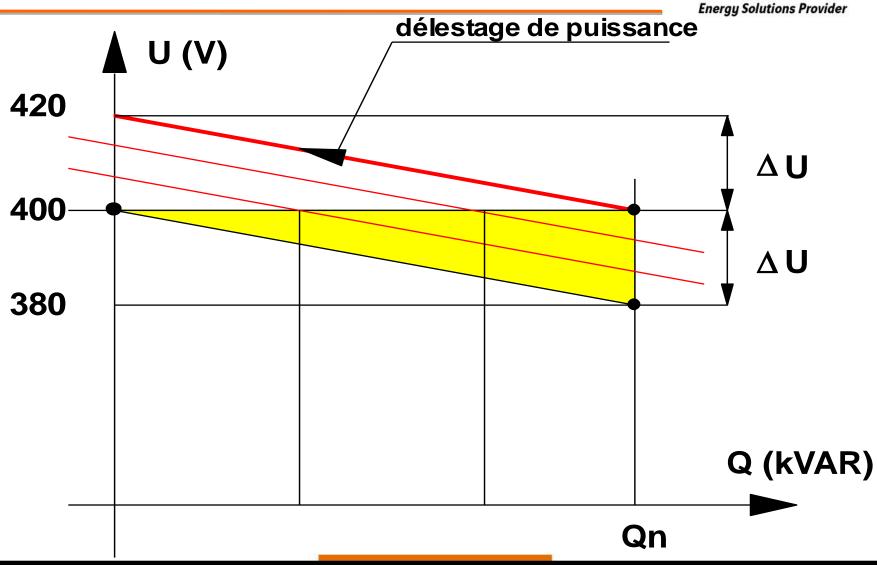
#### Speed droop





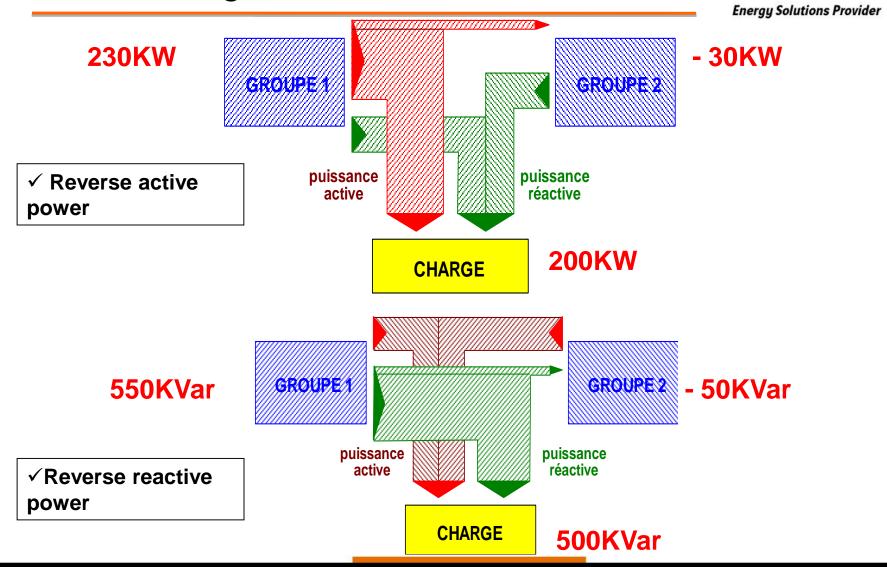
#### Voltage Droop





#### Load sharing Protection





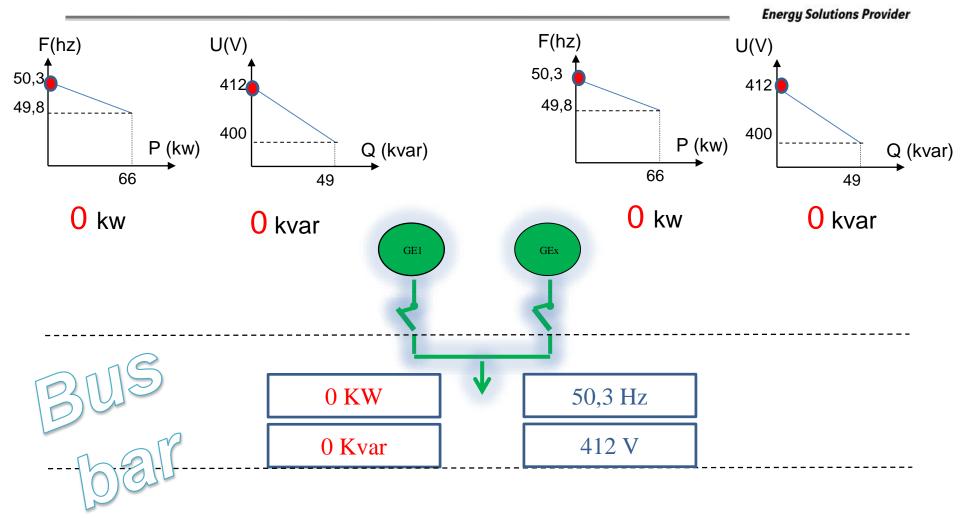


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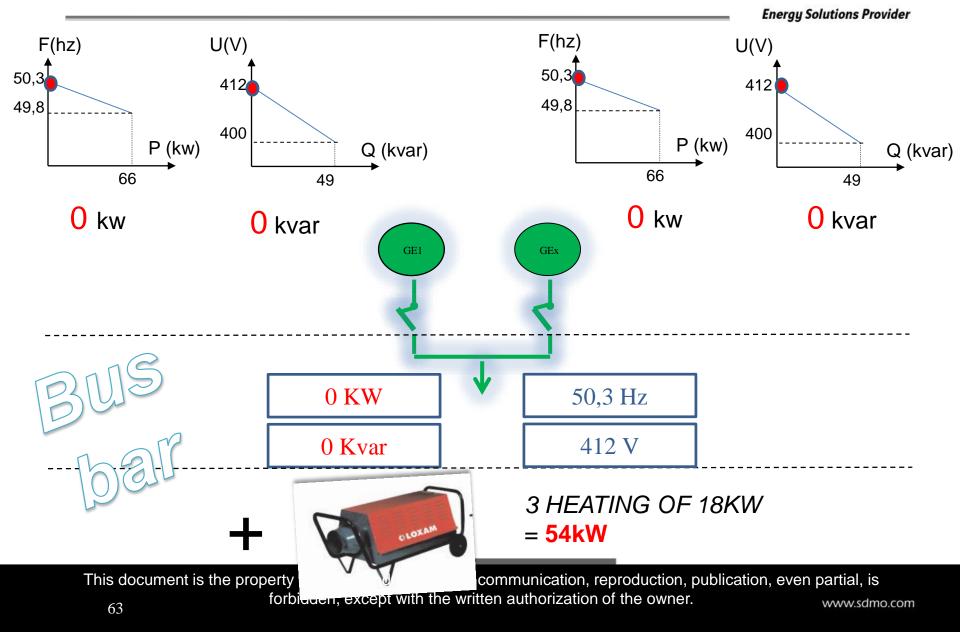
#### **Parallel mode**

# Simulation of load sharing

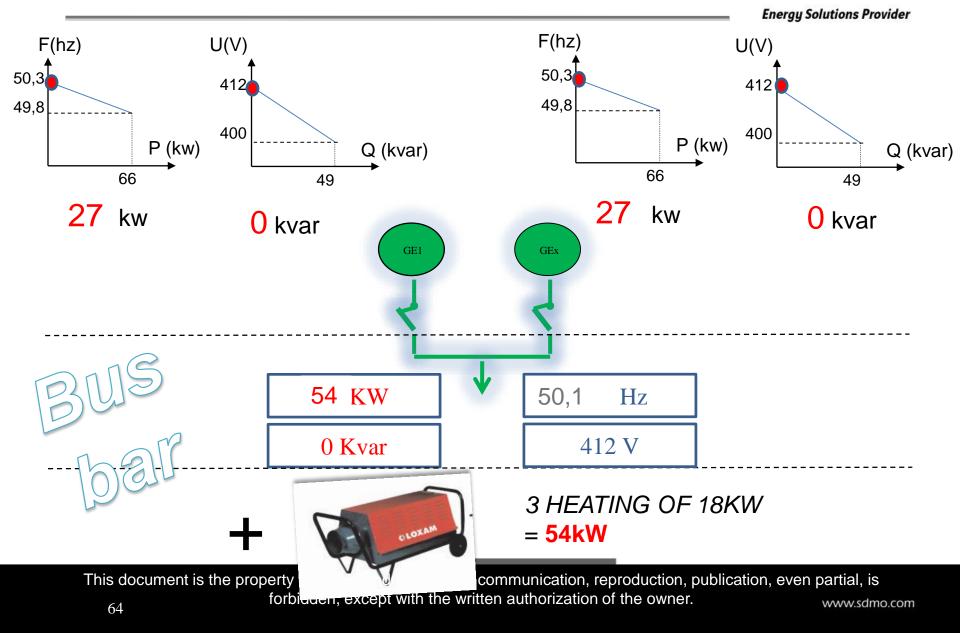




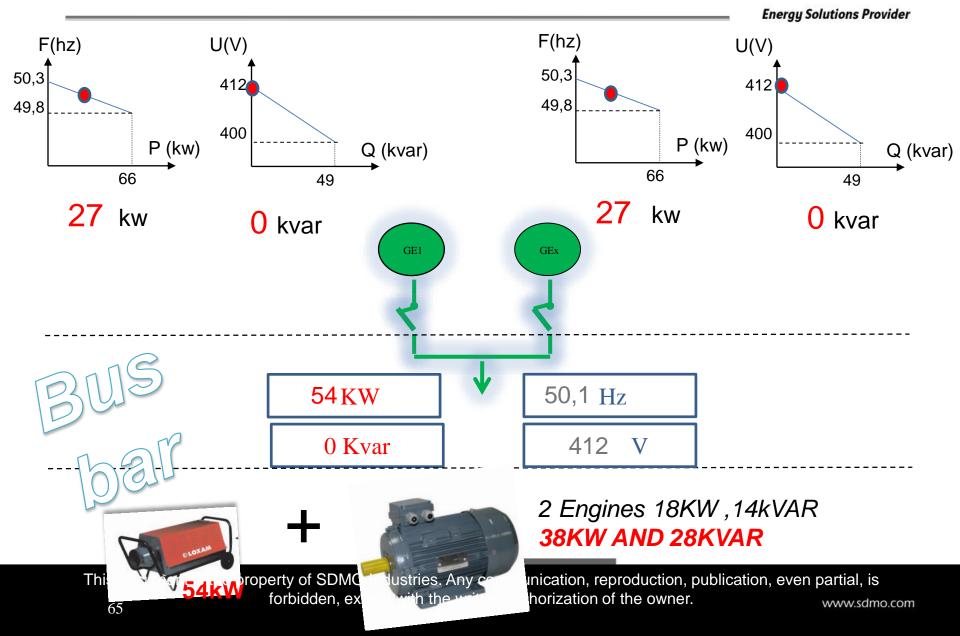




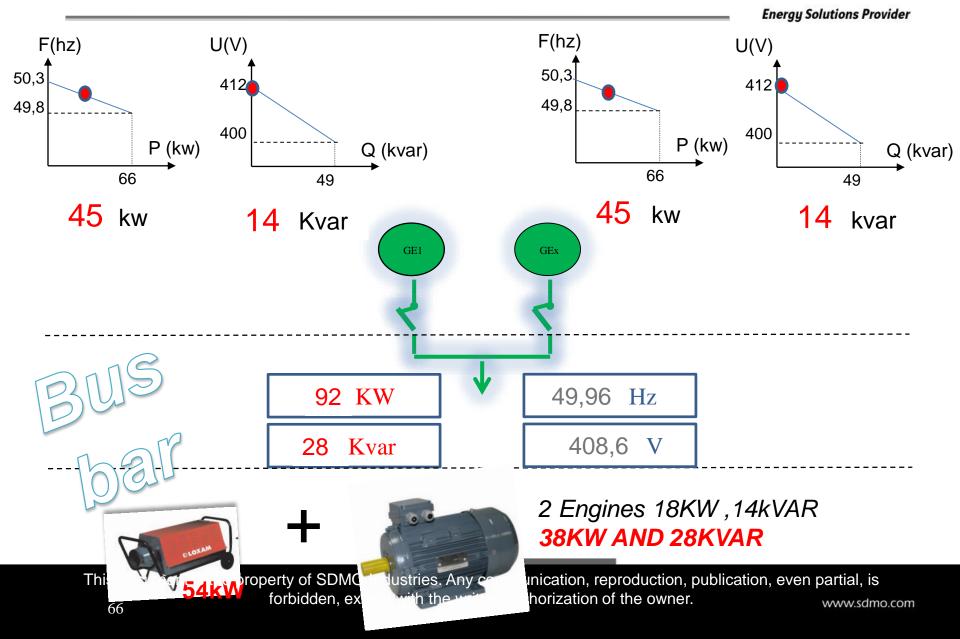














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#### Parallel mode

## Step by step

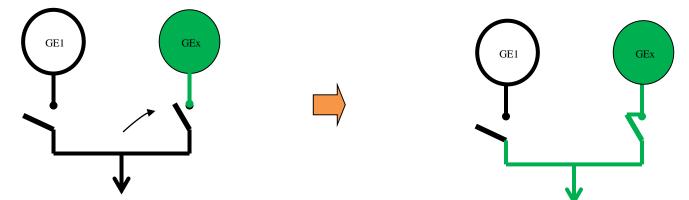
#### Paralleling steps

#### **Initial state**



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 $\checkmark$  The bus is supplied by a first genset. The second genset will synchronised automaticallt to the bus

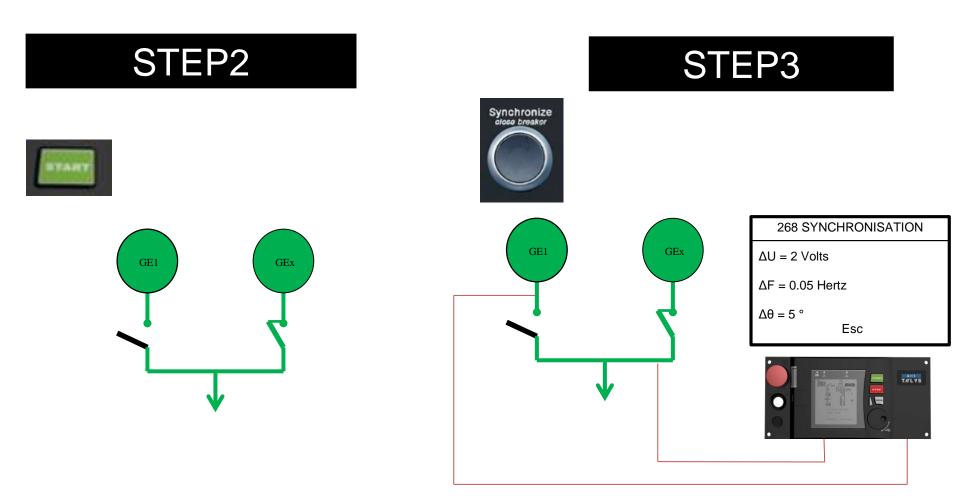




#### **Paralleling steps**



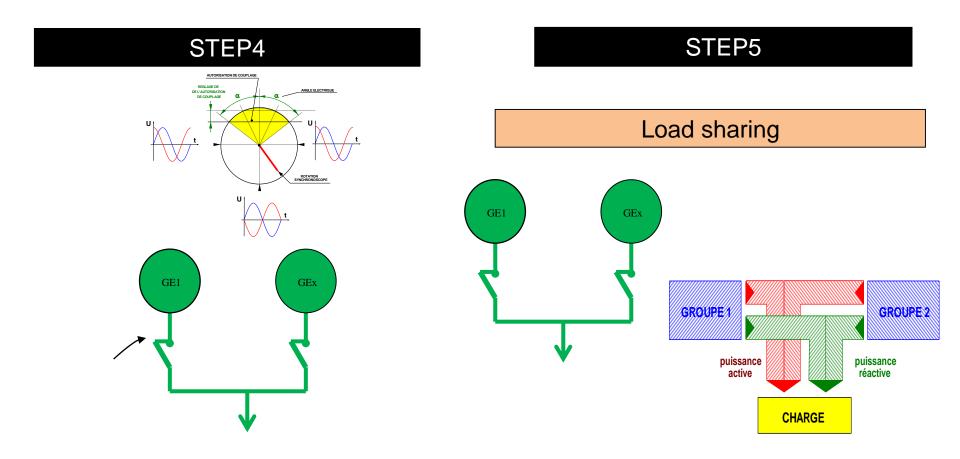
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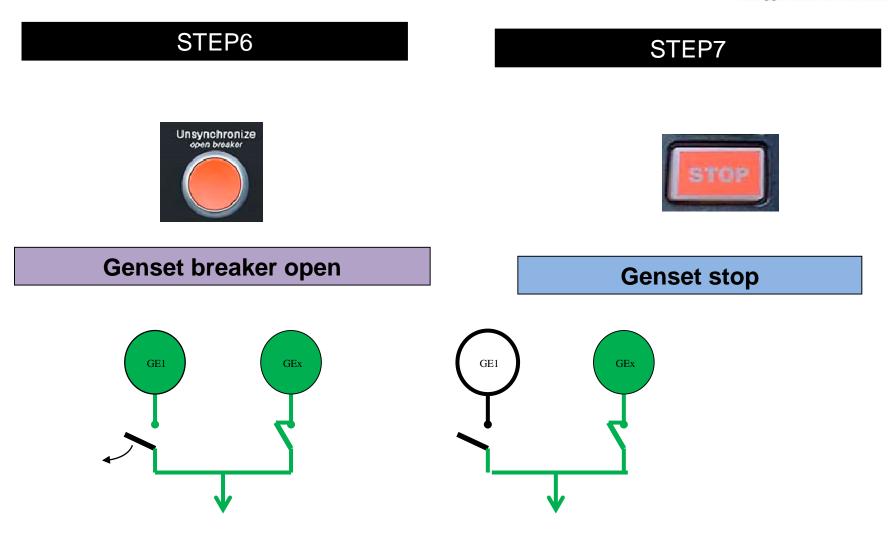
#### Paralleling steps



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## **Neutral Connection**

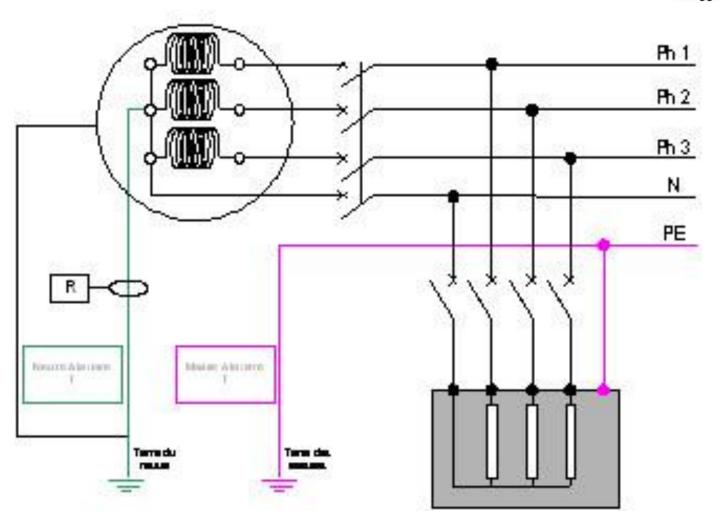


Reg	ime	Number of conductors	Detection	Note		
т	т	4 poles	Measure of residual current	Tripping at the 1 st default		
	С	3 poles	Without			
TN	S	4 poles	(Measure of residual current)	Tripping by the power breaker		

#### T.T grounding system



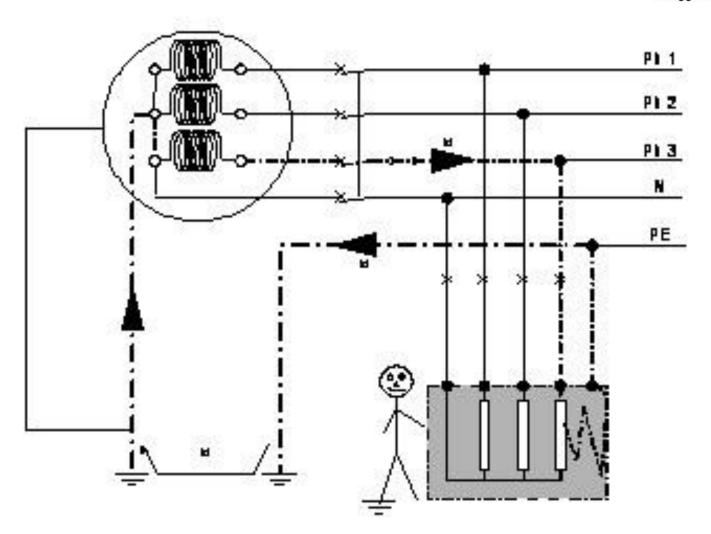
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#### Fault in TT grounding system



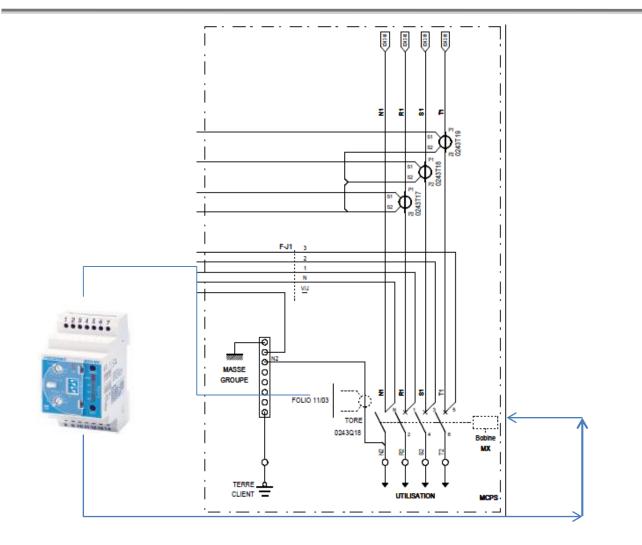
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#### TT – Single genset



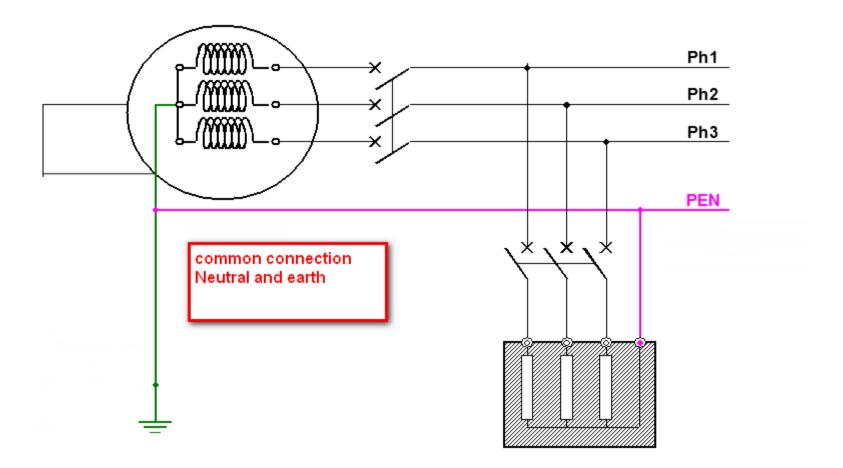
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TNC



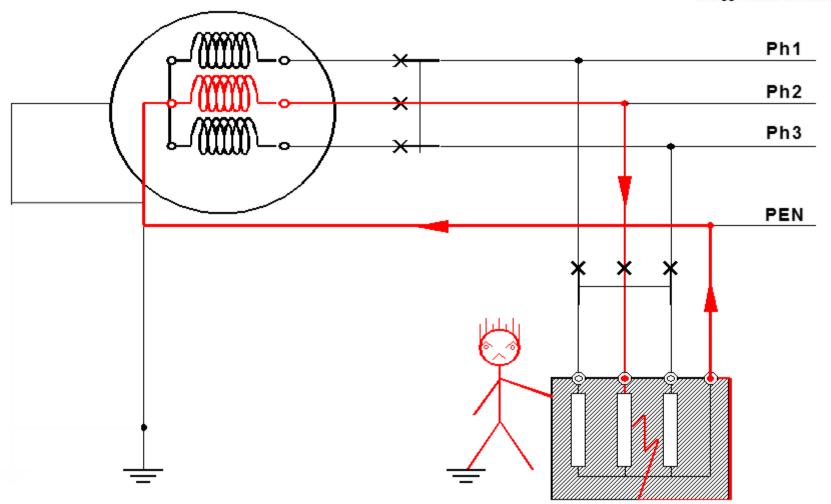
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#### **TNC FAULT**



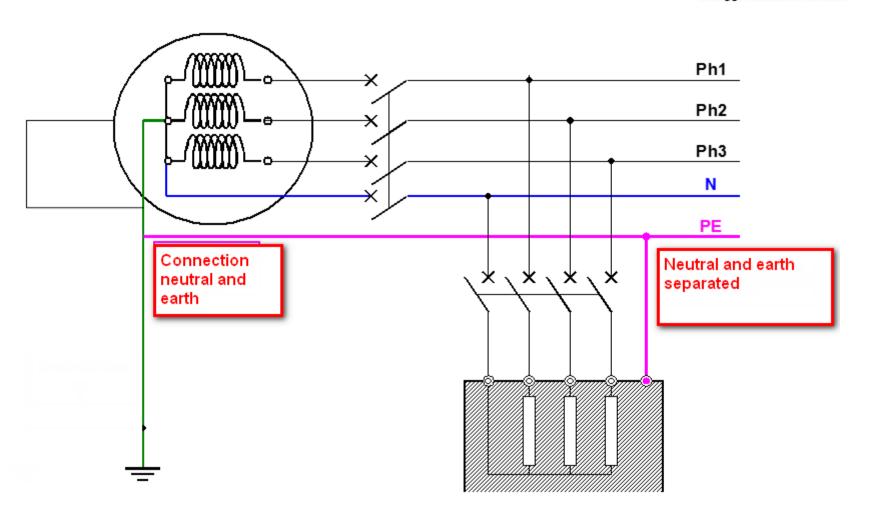
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**TNS** 



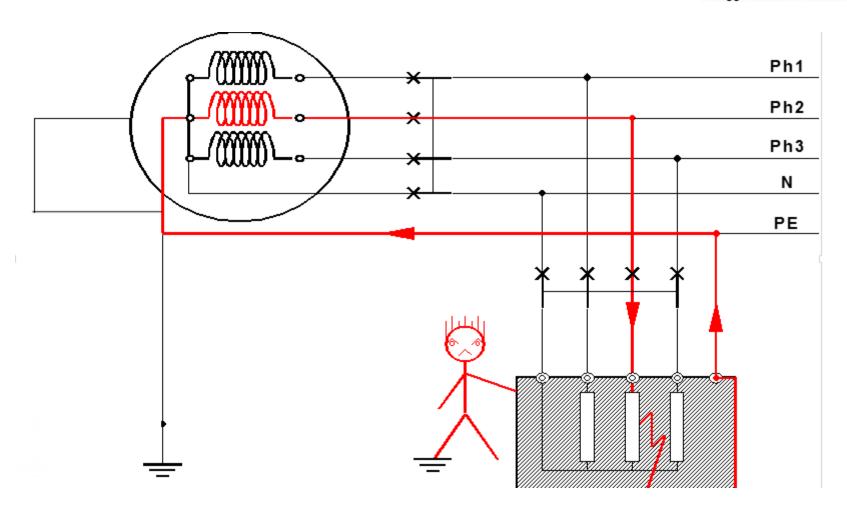
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#### **TNS FAULT**



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#### Parts identification



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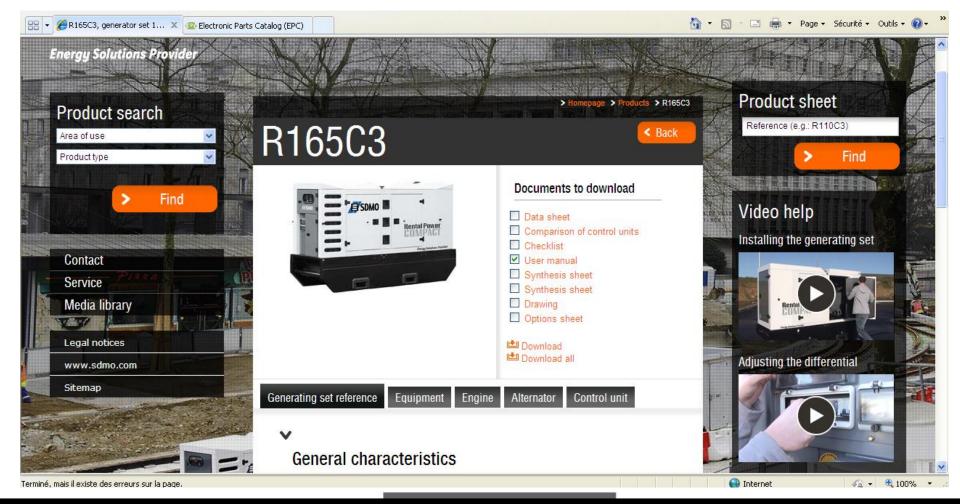
#### https://epc.sdmo.com

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Order		Info: Pos.	Material	Version	Description	Qty	Unit	Date from	Date to	Part list Info	:
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#### Thank you for your attention !

